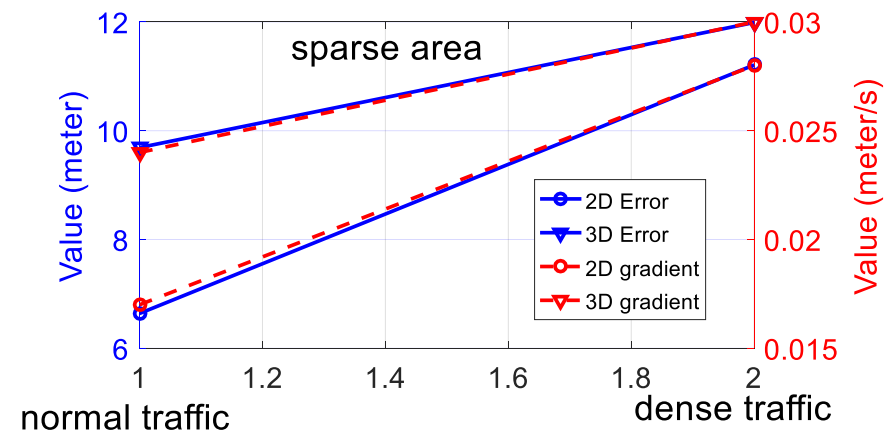
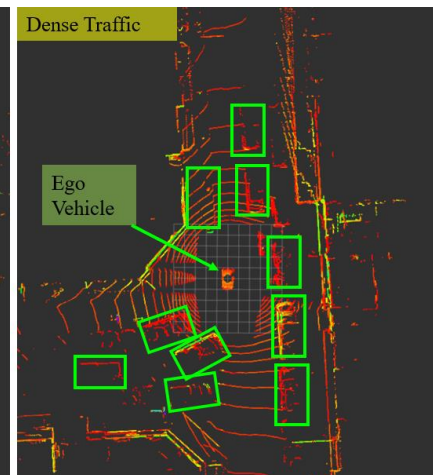
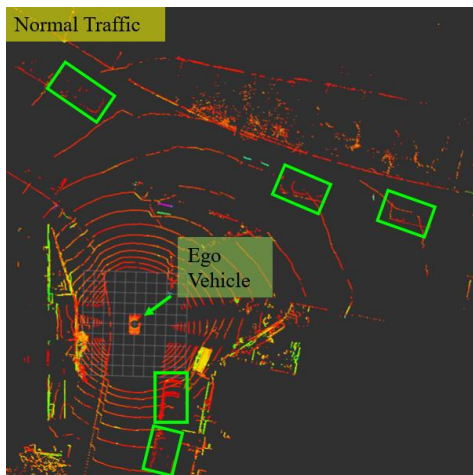
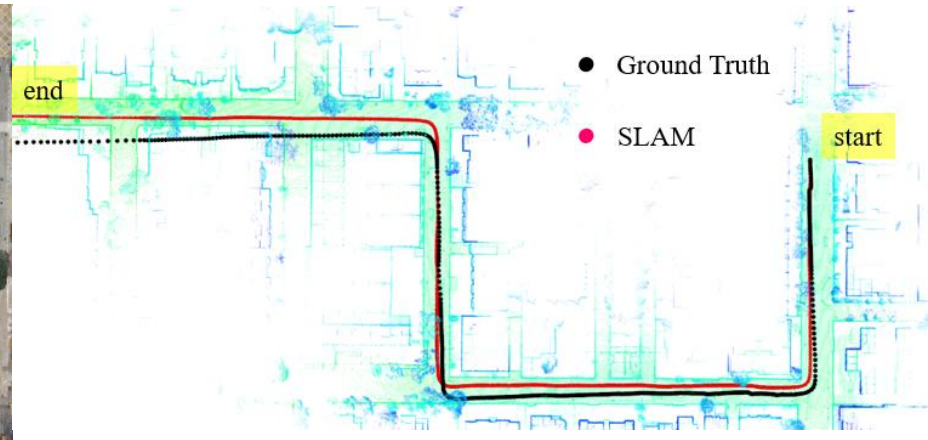
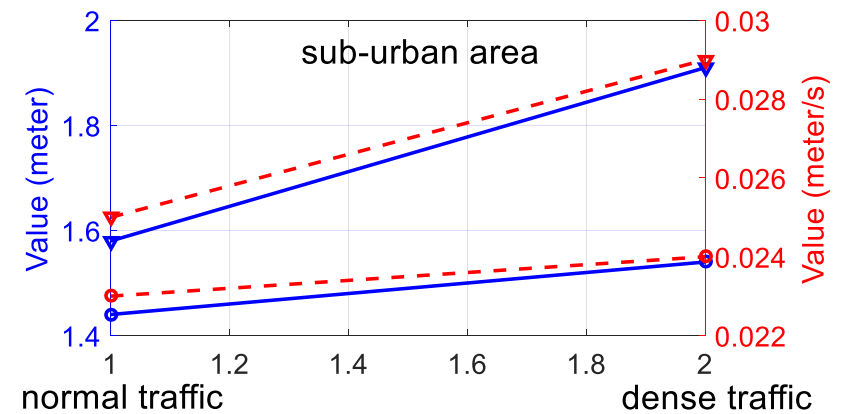
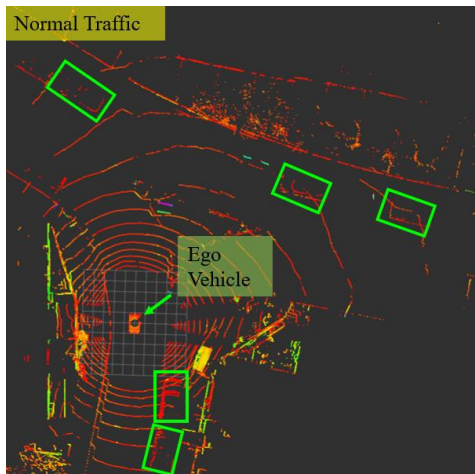
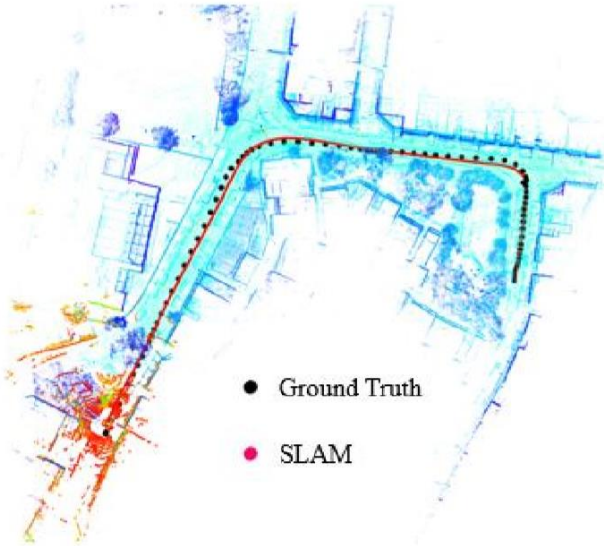


Analysis of NDT-based SLAM in Hong Kong

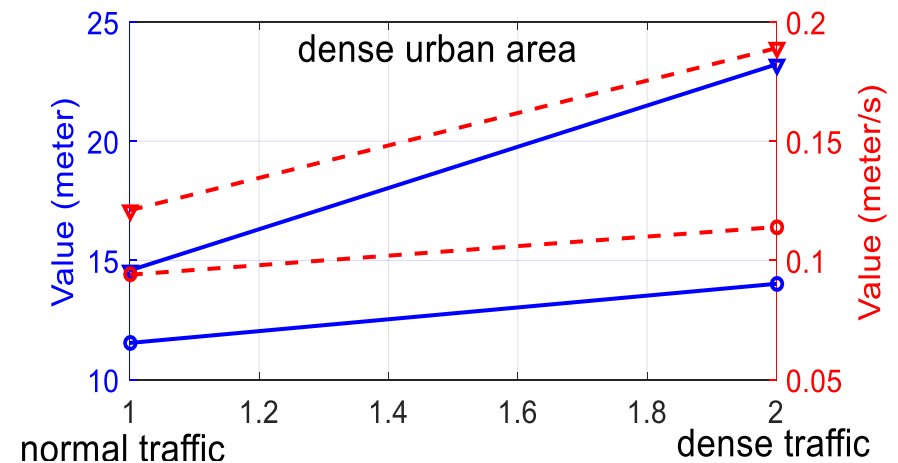
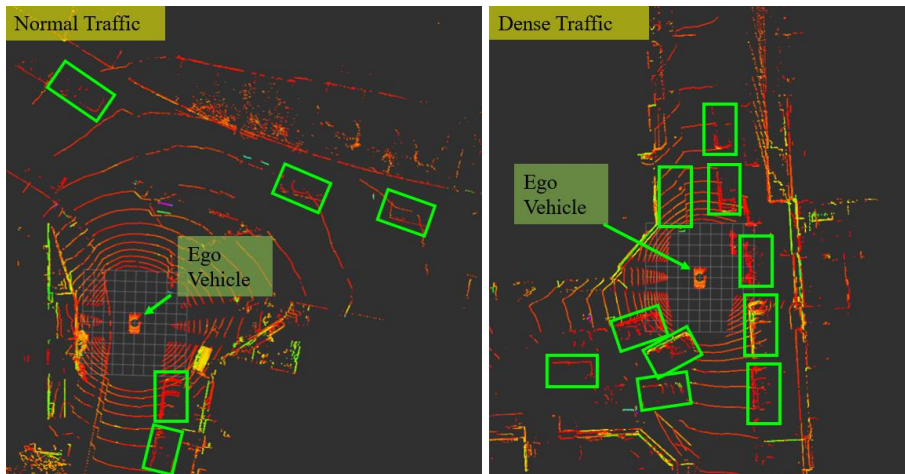
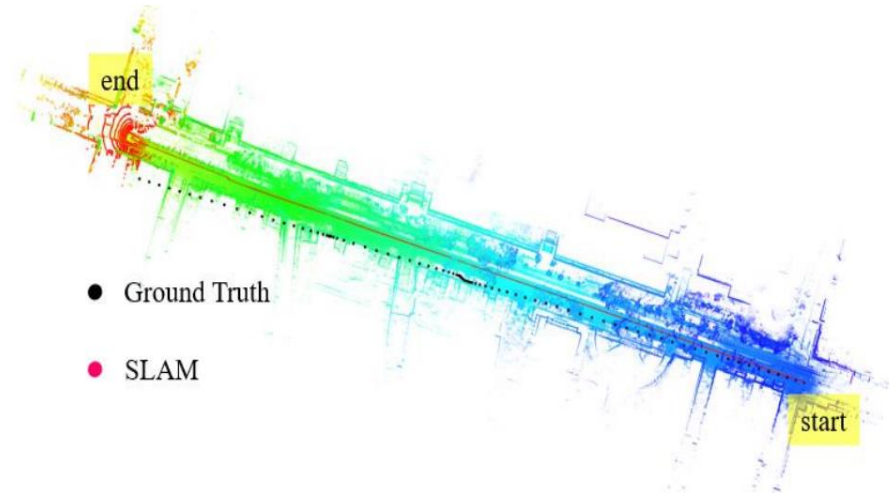
> **Sparse area** with dense traffic and normal traffic



sub-urban area with dense and normal traffic



Deep urban area with dense and normal traffic



Wen, W.; Hsu, L.-T.*; Zhang, G. (2018) [Performance analysis of NDT-based graph slam for autonomous vehicle in diverse typical driving scenarios of Hong Kong](#). Sensors 18:3928.